

# Efficiency Comparison of Modified Regression-Cum-Dual Mean Imputation Schemes for Estimating Population Mean Under Two-Phase Simple Random Sampling Using Simulation Studies

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**Abstract--** Auxiliary information has been widely used in survey sampling to improve the precision of estimators of population parameters, particularly when observations are missing. This study proposes modified regression-cum-dual mean imputation schemes for estimating the population mean under two-phase simple random sampling. The proposed estimators integrate the advantages of regression estimation and dual mean imputation to enhance estimation efficiency while minimizing bias and mean squared error (MSE). The theoretical properties of the estimators, including expressions for bias and MSE, are derived under first-order approximation. Their performance is evaluated through extensive Monte Carlo simulation studies conducted across different population settings that represent varying relationships between the study and auxiliary variables. The proposed estimators are compared with the conventional sample mean estimator, the regression imputation estimator, the dual mean imputation estimator, and other existing regression-cum-imputation estimators reported in the literature. Simulation results indicate that the proposed estimators consistently produce lower bias and MSE and achieve higher Percentage Relative Efficiency (PRE) than the competing estimators across the simulation scenarios considered. The findings demonstrate the robustness and superiority of the modified regression-cum-dual mean imputation schemes for handling missing data in two-phase simple random sampling. Consequently, the proposed estimators provide a reliable and efficient alternative for estimating the population means in practical survey sampling applications.

**Keywords--** Auxiliary information; Bias; Mean squared error; Missing data; Population means; Regression-cum-dual mean imputation; Simulation study; Two-phase simple random sampling.

## I. INTRODUCTION

Sampling theory is the field of statistics that is concerned with the collection, analysis and interpretation of data gathered from sampling the population under study.

The application of sampling theory is concerned not only with the proper selection of observations from the auxiliary variable. Many prominent authors developed several modified and improved ratio, regression, and exponential-type estimators using population information on the auxiliary variable  $x$ . However, the information about the population mean of the auxiliary variable is not always available. In the environment mentioned above, the most popular sampling scheme is the two-phase sampling scheme which was first established by Neyman (1938) to accumulate information on sampling. It is customarily acquired when the accumulation of information on a study variable is very costly but relatively cheaper to accumulate information on auxiliary variables that are correlated with the study variables. Due to these reasons, the two-phase sampling becomes a powerful and cost-effective scheme for obtaining the authentic estimate in the one-phase sample for the unknown parameters of the auxiliary variable. Authors like Kumar and Bahl (2006), Singh and Vishwakarma (2007), Singh (2011), Ozgul and Cingi (2014), Kalita *et al.* (2016), Noor-Al-Amin *et al.* (2016), Bazad and Bazad (2019), Bhushan and Gupta (2019), Adamu *et al.* (2019) and Bhushan *et al.* (2023) have extensively worked under two-phase sampling. However, the applicability of the aforementioned estimators depends on the full availability of sample information for both the study and auxiliary variables. Reduction in the sizes of sample information due to non-response decreases the efficiency of these estimators. In literature, Sukhatme (1962), Choudhury and Singh (2015), Audu and Adewara (2017a,b), Adamu *et al.* (2019) investigated the classical ratio estimator in two-phase sampling. Following Srivenkataraman (1980), Kumar and Bahl (2006) envisaged a class of dual-to-exponential-type ratio estimators using two phases. Singh and Vishwakarma (2007) investigated Bahl and Tuteja's (1991) exponential ratio and product estimators of population mean under two-phase sampling.

Singh (2011), Ozgul and Cingi (2014) developed a class of exponential regression cum ratio estimator in two-phase sampling. Kalita *et al.* (2016) proposed exponential ratio-cum-exponential dual-to-ratio estimators based on two-phase sampling. Following Kumar and Bahl (2006) and Kalita *et al.* (2016), Bazad and Bazad (2019) developed some classes of dual-to-ratio exponential-type estimators. Bhushan and Gupta (2019) provided some log-type estimators of population mean using two-phase sampling. Bhushan *et al.* (2021a) suggested some efficient classes of estimators. Bhushan *et al.* (2021b) developed some efficient classes of estimators under two-phase sampling. Recently, Bhushan and Kumar (2023) proposed a new, efficient class of estimators for the population mean using two-phase sampling.

## II. LITERATURE REVIEW

### 2.1 SOME EXISTING ESTIMATORS UNDER SRSWOR

The contributions of Cochran (1942), Deming (1956), Hurvitz (1952) and others helped lay the foundation for modern sampling theory. The work done during these periods made important contributions to modern sampling theory by suggesting methods of utilizing the auxiliary information for the purpose of estimating the population mean in order to increase the precision of the estimates.

To discuss some of the developed estimators in literature based on auxiliary variables, the following descriptions about the population and sample units were considered.

Let  $\Omega = (1, 2, 3 \dots N)$  be a population of size  $N$  and  $Y, X$  be two real valued functions having values  $(Y_i, X_i) \in \mathbb{R}^+$  on the  $i^{th}$  unit of  $U(1 = i = N)$ .

Let  $\bar{Y}$  and  $\bar{X}$  be the population means of  $Y$  and  $X$  respectively with  $C_y$  and  $C_x$  as coefficients of variation of  $Y$  and  $X$ .

Let a pair  $(y_i, x_i)$  of simple random sample of size  $n$  be drawn without replacement from the population  $\Omega = (1, 2, 3 \dots N)$  and  $\bar{y}, \bar{x}$  be sample means based on the sample drawn.

The usual sample mean  $\bar{y}$ , traditional ratio estimator  $\bar{y}_r$  (Cochran, 1942), product estimator  $\bar{y}_p$  (Murthy, 1964) and Dual to ratio estimator  $\bar{y}_{st}$  (Strivenkataramana, 1980) with their respective bias and variance/mean square error are defined as

$$\bar{y} = \frac{1}{n} \sum_{i=1}^n y_i \quad (2.1)$$

$$\text{var}(\bar{y}) = \frac{1-f}{n} \bar{Y}^2 C_y^2 \quad (2.2)$$

$$\bar{y}_r = \frac{\bar{y}}{\bar{x}} \bar{X} \quad (2.3)$$

$$\text{Bias}(\bar{y}_r) = \bar{Y} \frac{1-f}{n} [C_x^2 - \rho_{xy} C_x C_y] \quad (2.4)$$

$$\text{MSE}(\bar{y}_r) = \bar{Y}^2 \frac{1-f}{n} [C_y^2 + C_x^2 - 2\rho_{xy} C_x C_y] \quad (2.5)$$

$$\bar{y}_p = \frac{\bar{y}}{\bar{X}} \bar{x} \quad (2.6)$$

$$\text{Bias}(\bar{y}_p) = \bar{Y} \frac{1-f}{n} [C_x^2 + \rho_{xy} C_x C_y] \quad (2.7)$$

$$\text{MSE}(\bar{y}_p) = \bar{Y}^2 \frac{1-f}{n} [C_y^2 + C_x^2 + 2\rho_{xy} C_x C_y] \quad (2.8)$$

$$\bar{y}_{st} = \bar{y} \frac{N\bar{X} - n\bar{x}}{(N-n)\bar{X}} \quad (2.9)$$

$$\text{Bias}(\bar{y}_{st}) = \bar{Y} \frac{1-f}{n} \left[ \left( \frac{n}{N-n} \right)^2 C_x^2 - \frac{n}{N-n} \rho_{xy} C_x C_y \right] \quad (2.10)$$

$$\text{MSE}(\bar{y}_{st}) = \bar{Y}^2 \frac{1-f}{n} \left[ C_y^2 + \left( \frac{n}{N-n} \right)^2 C_x^2 - 2 \frac{n}{N-n} \rho_{xy} C_x C_y \right] \quad (2.11)$$

Where  $f = \frac{n}{N}$ ,  $f^* = \frac{n}{n_1}$ ,  $f_1 = \frac{n_1}{N}$ ,  
 $f^{**} = \frac{1-f}{n} + \frac{1-f_1}{n_1}$ ,  $C_{yx} = \rho_{xy} C_y / C_x$ ,  
 $C_{yz} = \rho_{yz} C_y / C_z$ ,  $C_{xz} = \rho_{xz} C_x / C_z$ .

The traditional ratio estimator  $\bar{y}_r$  and the dual to ratio estimator  $\bar{y}_{st}$  have higher efficiencies when the correlation between the study and auxiliary variables is strong and positive, while the product estimator  $\bar{y}_p$  has higher efficiency when the correlation between the study and auxiliary variables is strong and negative.

For estimating the population mean  $\bar{Y}$  of the study variate y, Singh and Espejo (2003) considered a linear combination of ratio and product estimators' type given by

$$\bar{y}_{RP} = \bar{y} \left[ k \frac{\bar{X}}{\bar{x}} + (1-k) \frac{\bar{x}}{\bar{X}} \right] \quad (2.12)$$

and obtained that the estimator attained optimality when  $k = \frac{(1+C)}{2}$  with  $C = C_y/C_x$ , where  $C_y$  is the coefficient of variation of y and  $C_x$  is the coefficient of variation of x.

Singh and Espejo (2007), modified that when the population mean  $\bar{X}$  of x is not known, a first-phase sample of size  $n_1$  should be drawn from the population on which only the x-characteristic is measured in order to furnish a good estimate of  $\bar{X}$ . Then a second-phase sample of size n is drawn on which both the variables y and x are measured. Let  $\bar{x}_1 = \frac{1}{n_1} \sum_{i=1}^{n_1} x_i$  denote the sample mean of x based on the first-phase sample of size  $n_1$ , Singh and Espejo (2007) considered a ratio-product type estimator in the two-phase sampling given by

$$\bar{y}_{RP}^{(d)} = \bar{y} \left[ k \frac{\bar{x}_1}{\bar{x}} + (1-k) \frac{\bar{x}}{\bar{x}_1} \right] \quad (2.13)$$

Choudhury and Singh (2012) consider the work of Singh and Espejo (2007) and modified a class chain ratio-product type estimator  $\bar{y}_{RP}^{(dc)}$  for estimating population mean  $\bar{Y}$  using two auxiliary characters under two conditions in Singh and Espejo (2007). The modified estimator, its bias and MSE are respectively given as

$$\bar{y}_{RP}^{(dc)} = \bar{y} \left[ k \frac{\bar{x}_1}{\bar{x}} \frac{\bar{Z}}{\bar{z}_1} + (1-k) \frac{\bar{x}}{\bar{x}_1} \frac{\bar{z}_1}{\bar{Z}} \right] \quad (2.14)$$

Subramani and Prabavathy (2014) modified two estimators of population mean based on median of study variable using auxiliary information as:

$$\bar{y}_{SP1} = \bar{y} \left[ \frac{M_d M + \bar{X}}{M_d m + \bar{X}} \right] \quad (2.35)$$

$$\bar{y}_{SP2} = \bar{y} \left[ \frac{\bar{X} M + M_d}{\bar{X} m + M_d} \right] \quad (2.36)$$

where  $M$ ,  $M_d$  and  $m$  are the median of the study variable, the median of the auxiliary variable, and the sample median of the study variable, respectively. The MSEs of modified estimators are given below;

$$MSE(\bar{y}_{SPi}) = \text{var}(\bar{y}) + R_m^2 \phi_i^2 \text{var}(m) - 2R_m \phi_i \text{cov}(\bar{y}, m) \quad i=1,2 \quad (2.37)$$

where  $R_m = \bar{Y} / M$ ,  $\phi_1 = MM_d / (MM_d + \bar{X})$  and  $\phi_2 = \bar{X} M / (\bar{X} M + M_d)$ .

Singh (2015) modified an improved class of ratio type estimator for finite population mean using unknown weight and power transformation strategies. The particular cases of this estimator are Walsh (1970) estimator at  $k=1$  and  $\alpha=w$ , Ray et al., (1979) estimator at  $k=-1$  and  $\alpha=-\gamma$ , Srivenkataramana and Tracy (1979) at  $k=-1$  and  $\alpha=1-f$ , Srivenkataramana and Tracy (1979) at  $k=-1$  and  $\alpha=-n/(N-n)$  and Srivenkataramana (1980) at  $k=-1$  and  $\alpha=1-w$ . The modified estimator and its properties are given below;

$$\bar{y}_{RVK} = \bar{y} \left[ \frac{\sqrt{\bar{X}}}{\alpha\sqrt{\bar{x}} + (1-\alpha)\sqrt{\bar{X}}} \right]^K \quad (2.38)$$

$$Bias(\bar{y}_{RVK}) = \bar{Y} \frac{1-f}{n} \left[ \left( \frac{k(k+1)}{4} \alpha^2 + \frac{1}{8} k\alpha \right) C_x^2 - \frac{1}{2} k\alpha\rho_{xy} C_x C_y \right] \quad (2.39)$$

$$MSE(\bar{y}_{RVK}) = \bar{Y}^2 \frac{1-f}{n} \left[ C_y^2 + \frac{1}{4} k^2 \alpha^2 C_x^2 - k\alpha\rho_{xy} C_x C_y \right] \quad (2.40)$$

In his study, the modified estimators attain the optimality when  $\alpha k = 2\rho_{xy} C_y / C_x$ . The empirical study in his work revealed that the modified estimator is more efficient than the estimators of Walsh (1979), Ray *et al.*, (1979), Srivenkataramana and Tracy (1979), Srivenkataramana (1980).

### III. MATERIALS AND METHODS

#### 3.1 Robust Outlier-Free Measure to be used in the Study

The study will utilize robust, outlier-resistant parameter estimation techniques to minimize or eliminate the influence of extreme values in the sample data. These methods include:

- i. Gini's Mean Difference method
- ii. Downton's Method
- iii. The Method of Probability-Weighted Moments

##### 3.1.1 Gini's Mean Method

Let  $\Delta_{xi} = X_{(i+1)} - X_{(i)}$ , where  $X_{(i)}$  is the order statistics so that  $\Delta_{xi}, i=1, \dots, n-1$  is the distance between adjacent observations. Then Gini's mean method proposed by Nair (1936) is given as

$$G = \frac{4}{n-1} \sum_{i=1}^n \left( \frac{2i-n-1}{2n} \right) X_{(i)} \quad (3.1)$$

##### 3.1.2 Downton's Method

Let  $X_1, X_2, \dots, X_n$ , be a random sample from a normal distribution with mean  $\mu$  and variance  $\sigma^2$ ; that is,  $X_1, X_2, \dots, X_n \sim N(\mu, \sigma^2)$ . Let  $X_{(1)} \leq X_{(2)} \leq \dots X_{(n)}$  denote the corresponding order statistics.

The Downton estimator,  $D$  proposed by Downton (1966), is given as

$$D = C \sum_{i=1}^n \frac{(2i-n-1)X_{(i)}}{n(n-1)} \quad (3.2)$$

Where  $C = \sqrt{\pi} = 1.772453851$  for a normal distribution and does not depend on the sample size  $n$ .

##### 3.1.3 Method of probability weighted moments

Let  $X_1, X_2, \dots, X_n$ , be a random sample from a normal distribution with mean  $\mu$  and variance  $\sigma^2$ ; that is,  $X_1, X_2, \dots, X_n \sim N(\mu, \sigma^2)$ .

Let  $X_{(1)} \leq X_{(2)} \leq \dots X_{(n)}$  denote the corresponding order statistics. The PWMs is defined by Greenwood *et al.* (1979) and is given as

$$S_{pw} = \frac{\sqrt{\pi}}{n^2} \sum_{i=1}^n (2i-n-1)X_{(i)} \quad (3.3)$$

#### 3.2 PROPOSED IMPUTATION SCHEMES

Having studied the work of Audu *et al.*, (2021b) and Musa *et al.* (2023), based on the identified weaknesses listed in chapter one, the following two imputation schemes are proposed.

Let  $\Omega$  be a population with  $N$  units,  $\Phi \subset \Omega$  with cardinality  $|\Phi| = r$  and  $\Phi^c$  be complement of  $\Phi$ . Let  $S_1$  be a set of preliminary sample observations of size  $n_1$  ( $n_1 < n$ ) from which  $\bar{x}_1$ , the unbiased estimate of  $\bar{X}$ , the population mean of  $X$ , is estimated. Let  $S_2$  be a set of sample of size  $n_2$  ( $n_2 < n_1$ ) of which only  $r$  ( $r < n_2$ ) elements respond.

$$y_i = \begin{cases} y_i & \text{if } i \in R \\ n(\bar{y}_r + \hat{\beta}_{rg}(\bar{x}_1^* - \bar{x}_r)) \exp \left( \frac{H_r \left( 1 - \frac{\bar{x}_r}{\bar{x}_1^*} \right)}{1 + ((\phi_j \bar{x}_r + \phi_k) / (\phi_j \bar{x}_1^* + \phi_k))} \right) - r\bar{y}_r \left\{ \frac{x_i}{\sum_{i \in R} x_i} \right\} & \text{if } i \in R^c \end{cases} \quad (3.5)$$

$$y_i = \begin{cases} y_i & \text{if } i \in R \\ \left[ \bar{y}_r \left( \frac{\phi_j \bar{x}_i^* + \phi_k}{\phi_j \bar{x}_r + \phi_k} \right) \exp \left( \frac{H_s \left( 1 - \frac{\bar{x}_r}{\bar{x}_i} \right)}{1 + \left( \phi_j \bar{x}_r + \phi_k \right) / \left( \phi_j \bar{x}_i^* + \phi_k \right)} \right) - \bar{r} \bar{y}_r \right] \frac{x_i}{\sum_{i \in R'} x_i} & \text{if } i \in R^c \end{cases} \quad (3.6)$$

$$y_i = \begin{cases} y_i & \text{if } i \in R \\ n \left( \bar{y}_r + \hat{\beta}_s (\bar{x}_i - \bar{x}_r) \right) \left( \frac{\phi_j \bar{x}_i^* + \phi_k}{\phi_j \bar{x}_r + \phi_k} \right) \exp \left( \frac{H_s \left( 1 - \frac{\bar{x}_r}{\bar{x}_i} \right)}{1 + \left( \phi_j \bar{x}_r + \phi_k \right) / \left( \phi_j \bar{x}_i^* + \phi_k \right)} \right) - \bar{r} \bar{y}_r \right] \frac{x_i}{\sum_{i \in R'} x_i} & \text{if } i \in R^c \end{cases} \quad (3.7)$$

where  $\bar{x}_1^* = \frac{n_1 \bar{x}_1 - n \bar{x}}{n_1 - n}$ ,  $H_s = \phi_j \bar{x}_1^* / (\phi_j \bar{x}_1^* + \phi_k)$ ,

$$\Gamma = \{(G \times n), (D \times n), (S_{pw} \times n)\}, \phi_j, \phi_k \in \Gamma,$$

$a = 1, 2, 3, 4, 5, 6$ .  $G, D$  and  $S_{pw}$  are the Gini's mean difference, Downtown's method and Probability weighted moments, which are the nonconventional robust measures free from the influence of outliers.

### 3.2.1 Assumption Of The Proposed Imputation Schemes

The assumptions of proposed imputation schemes are:

- The size of the studied population is finite, ( $N < \infty$ )
- Characteristic of interest (Y) and auxiliary characteristics (X) are measurable
- Correlation between X and Y is strong.

$$\bar{y}_r \neq 0, \bar{x}_r \neq 0, \bar{x}_1 \neq 0$$

## IV. DATA ANALYSIS AND DISCUSSION OF RESULT

To empirically validate the performance of the proposed modified regression-cum-dual mean imputation estimators, four simulated population datasets representing different sampling conditions were generated. The simulation study was designed to evaluate the robustness and efficiency of the proposed estimators under two-phase simple random sampling by considering varying population characteristics and relationships between the study and auxiliary variables.

The proposed estimators were compared with selected existing estimators using three standard performance measures: Bias, Mean Squared Error (MSE), and Percentage Relative Efficiency (PRE).

Bias was used to assess the accuracy of each estimator by measuring the extent to which the estimated population mean deviated from the true population mean. The MSE, which incorporates both the variance and squared bias of an estimator, served as a comprehensive measure of estimation precision. Percentage Relative Efficiency (PRE) was computed to compare the efficiency of the proposed estimators relative to the existing estimators, with higher PRE values indicating superior performance.

The combined use of these evaluation criteria provides a comprehensive framework for assessing estimator performance. The simulation results offer empirical evidence of the effectiveness, robustness, and potential superiority of the proposed modified regression-cum-dual mean imputation schemes for estimating the population mean under two-phase simple random sampling.

### 4.1 Populations used for Simulation Study for positive relationship

**Table 1: Biases, MSEs and PREs of Existing Estimators and Proposed Estimators of the proposed schemes 1, 2 and 3 using  $N=2000, n_1=800, n=300, r=200$  (Case 1 & 2)**

| Estimators                             | Case 1   |         |          | Case 2   |         |          |
|----------------------------------------|----------|---------|----------|----------|---------|----------|
|                                        | Biases   | MSEs    | PREs     | Biases   | MSEs    | PREs     |
| Sample mean T0                         | 0.00974  | 0.029   | 100.0000 | 0.00016  | 0.0298  | 100      |
| Lee et al. (1994) T1                   | -0.00107 | 0.0102  | 284.2900 | -0.00471 | 0.01019 | 292.3500 |
| Singh & Horn (2000) T2                 | -0.00265 | 0.00994 | 291.8400 | -0.00543 | 0.01088 | 273.8100 |
| Kadilar & Cingi (2008) T3              | 0.01267  | 0.02634 | 110.1000 | 0.02825  | 0.04539 | 65.6500  |
| Singh (2009) T4                        | 0.00133  | 0.01002 | 289.5600 | 0.00058  | 0.01134 | 262.8300 |
| Aduu et al. (2021b) T5                 | -0.02768 | 0.01163 | 249.4300 | -0.04152 | 0.01544 | 192.9900 |
| <b>Musa et al. (2023)</b>              |          |         |          |          |         |          |
| T6 (a=Cx,b=Sx)                         | -1.08465 | 1.25058 | 2.3200   | -1.09581 | 1.26833 | 2.3500   |
| T6 (a=Cx,b=Skw)                        | -1.18521 | 1.47997 | 1.9600   | -1.19667 | 1.50113 | 1.9800   |
| T6 (a=Cx,b=Kurt)                       | -1.20351 | 1.52412 | 1.9000   | -1.2151  | 1.5463  | 1.9300   |
| T6 (a=Sx,b=Cx)                         | -1.2069  | 1.5324  | 1.8900   | -1.21852 | 1.55478 | 1.9200   |
| T6 (a=Sx,b=Skw)                        | -1.20694 | 1.53248 | 1.8900   | -1.21855 | 1.55486 | 1.9200   |
| T6 (a=Sx,b=Kurt)                       | -1.20916 | 1.53792 | 1.8900   | -1.22079 | 1.56043 | 1.9100   |
| T6 (a=Skw,b=Sx)                        | -1.08394 | 1.24905 | 2.3200   | -1.09511 | 1.26679 | 2.3500   |
| T6 (a=Skw,b=Cx)                        | -1.1847  | 1.47874 | 1.9600   | -1.19615 | 1.49987 | 1.9900   |
| T6 (a=Skw,b=Kurt)                      | -1.20344 | 1.52395 | 1.9000   | -1.21502 | 1.54612 | 1.9300   |
| T6 (a=Kurt,b=Cx)                       | -1.13035 | 1.35207 | 2.1400   | -1.14157 | 1.37098 | 2.1700   |
| T6 (a=Kurt,b=Sx)                       | -1.09982 | 1.09422 | 2.6500   | -1.0211  | 1.11102 | 2.6800   |
| T6 (a=Kurt,b=Skw)                      | -1.13097 | 1.35346 | 2.1400   | -1.14219 | 1.3724  | 2.1700   |
| <b>Estimators of Proposed Scheme 1</b> |          |         |          |          |         |          |
| Tp11 (G,D)                             | -0.00293 | 0.00959 | 302.3200 | -0.00521 | 0.00993 | 300.0000 |
| Tp12 (G,S)                             | -0.00311 | 0.00965 | 300.6500 | -0.005   | 0.01024 | 290.9600 |
| Tp13 (D,G)                             | -0.00323 | 0.00972 | 298.4500 | -0.00479 | 0.01053 | 282.8800 |
| Tp14 (D,S)                             | -0.00328 | 0.00976 | 297.2700 | -0.00468 | 0.01067 | 279.2400 |
| Tp15 (S,G)                             | -0.00303 | 0.00962 | 301.6000 | -0.0051  | 0.01009 | 295.4400 |
| Tp16 (S,D)                             | -0.0029  | 0.00959 | 302.4800 | -0.00524 | 0.00989 | 301.3200 |
| <b>Estimators of Proposed Scheme 2</b> |          |         |          |          |         |          |
| Tp21 (G,D)                             | 0.01144  | 0.03097 | 93.6300  | 0.00188  | 0.03217 | 92.6300  |
| Tp22 (G,S)                             | 0.01264  | 0.0324  | 89.5200  | 0.00312  | 0.0339  | 87.9000  |
| Tp23 (D,G)                             | 0.01363  | 0.0336  | 86.3000  | 0.00416  | 0.03538 | 84.2300  |
| Tp24 (D,S)                             | 0.01407  | 0.03413 | 84.9600  | 0.00461  | 0.03603 | 82.6900  |
| Tp25 (S,G)                             | 0.01206  | 0.0317  | 91.4700  | 0.00252  | 0.03305 | 90.1500  |
| Tp26 (S,D)                             | 0.01126  | 0.03075 | 94.2900  | 0.0017   | 0.0319  | 93.3900  |
| <b>Estimators of Proposed Scheme 3</b> |          |         |          |          |         |          |
| Tp31 (G,D)                             | -0.00219 | 0.00965 | 300.5000 | -0.00558 | 0.00934 | 319.0300 |
| Tp32 (G,S)                             | -0.0019  | 0.00974 | 297.6400 | -0.00564 | 0.00924 | 322.4900 |
| Tp33 (D,G)                             | -0.00165 | 0.00985 | 294.5000 | -0.00566 | 0.0092  | 323.9800 |
| Tp34 (D,S)                             | -0.00154 | 0.0099  | 292.9400 | -0.00566 | 0.00919 | 324.2300 |
| Tp35 (S,G)                             | -0.00204 | 0.00969 | 299.1500 | -0.00561 | 0.00928 | 321.0400 |
| Tp36 (S,D)                             | -0.00224 | 0.00964 | 300.8400 | -0.00557 | 0.00936 | 318.3400 |

**Table 2: Biases, MSEs and PREs of Existing Estimators and Proposed Estimators of the proposed schemes 1, 2 and 3 using N=2000,**

**$n_1=1000, n=500, r=300$  (Case 1 & 2)**

| Estimators                             | Case 1   |         |        | Case 2   |         |        |
|----------------------------------------|----------|---------|--------|----------|---------|--------|
|                                        | Biases   | MSEs    | PREs   | Biases   | MSEs    | PREs   |
| Sample mean $T_0$                      | -0.00227 | 0.01853 | 1.00   | -0.00277 | 0.01875 | 1.00   |
| Lee <i>et al.</i> (1994) $T_1$         | -0.00414 | 0.00423 | 438.36 | -0.00157 | 0.00645 | 290.86 |
| Singh & Horn (2000) $T_2$              | -0.00441 | 0.00407 | 454.81 | -0.00221 | 0.00685 | 273.55 |
| Kadilar & Cingi (2008) $T_3$           | -0.01484 | 0.01824 | 101.6  | 0.01666  | 0.02677 | 70.04  |
| Singh (2009) $T_4$                     | -0.00115 | 0.00411 | 450.69 | 0.00135  | 0.00699 | 268.38 |
| Audu <i>et al.</i> (2021b) $T_5$       | -0.02433 | 0.00531 | 348.68 | -0.0247  | 0.00846 | 221.71 |
| <b>Musa <i>et al.</i> (2023)</b>       |          |         |        |          |         |        |
| $T_6$ ( $a=Cx, b=Sx$ )                 | -0.99812 | 1.02416 | 1.81   | -0.97778 | 0.99538 | 1.88   |
| $T_6$ ( $a=Cx, b=Skw$ )                | -1.12083 | 1.28358 | 1.44   | -1.1005  | 1.25366 | 1.5    |
| $T_6$ ( $a=Cx, b=Kurt$ )               | -1.14291 | 1.33356 | 1.39   | -1.12257 | 1.30354 | 1.44   |
| $T_6$ ( $a=Sx, b=Cx$ )                 | -1.14699 | 1.34293 | 1.38   | -1.12666 | 1.31289 | 1.43   |
| $T_6$ ( $a=Sx, b=Skw$ )                | -1.14703 | 1.34303 | 1.38   | -1.1267  | 1.31299 | 1.43   |
| $T_6$ ( $a=Sx, b=Kurt$ )               | -1.14971 | 1.34918 | 1.37   | -1.12638 | 1.31913 | 1.42   |
| $T_6$ ( $a=Skw, b=Sx$ )                | -0.99725 | 1.02243 | 1.81   | -0.97691 | 0.99367 | 1.89   |
| $T_6$ ( $a=Skw, b=Cx$ )                | -1.12021 | 1.28219 | 1.45   | -1.09988 | 1.25227 | 1.5    |
| $T_6$ ( $a=Skw, b=Kurt$ )              | -1.14282 | 1.33337 | 1.39   | -1.12249 | 1.30334 | 1.44   |
| $T_6$ ( $a=Kurt, b=Cx$ )               | -1.05418 | 1.13884 | 1.63   | -1.03384 | 1.10943 | 1.69   |
| $T_6$ ( $a=Kurt, b=Sx$ )               | -0.90522 | 0.84804 | 2.18   | -0.88493 | 0.82079 | 2.28   |
| $T_6$ ( $a=Kurt, b=Skw$ )              | -1.05493 | 1.14042 | 1.62   | -1.03459 | 1.111   | 1.69   |
| <b>Estimators of Proposed Scheme 1</b> |          |         |        |          |         |        |
| $Tp11$ (G,D)                           | -0.00472 | 0.00392 | 472.18 | -0.00221 | 0.00697 | 268.78 |
| $Tp12$ (G,S)                           | -0.00462 | 0.00402 | 460.55 | -0.0021  | 0.00726 | 258.38 |
| $Tp13$ (D,G)                           | -0.00452 | 0.00414 | 447.8  | -0.00198 | 0.00752 | 249.15 |
| $Tp14$ (D,S)                           | -0.00446 | 0.0042  | 441.54 | -0.00193 | 0.00765 | 245.03 |
| $Tp15$ (S,G)                           | -0.00467 | 0.00397 | 466.73 | -0.00216 | 0.00711 | 263.53 |
| $Tp16$ (S,D)                           | -0.00473 | 0.00391 | 473.57 | -0.00223 | 0.00694 | 270.31 |
| <b>Estimators of Proposed Scheme 2</b> |          |         |        |          |         |        |
| $Tp21$ (G,D)                           | -0.00096 | 0.0203  | 91.26  | 0.00419  | 0.02055 | 91.22  |
| $Tp22$ (G,S)                           | -0.00002 | 0.0216  | 85.78  | 0.00524  | 0.02188 | 85.67  |
| $Tp23$ (D,G)                           | 0.00079  | 0.02271 | 81.58  | 0.00614  | 0.02303 | 81.4   |
| $Tp24$ (D,S)                           | 0.00114  | 0.0232  | 79.85  | 0.00654  | 0.02354 | 79.63  |
| $Tp25$ (S,G)                           | -0.00048 | 0.02097 | 88.37  | 0.00473  | 0.02123 | 88.3   |
| $Tp26$ (S,D)                           | -0.00111 | 0.02011 | 92.15  | 0.00404  | 0.02035 | 92.12  |
| <b>Estimators of Proposed Scheme 3</b> |          |         |        |          |         |        |
| $Tp31$ (G,D)                           | -0.00481 | 0.00389 | 476.51 | -0.00237 | 0.00645 | 290.58 |
| $Tp32$ (G,S)                           | -0.00477 | 0.00396 | 467.51 | -0.00233 | 0.00637 | 294.16 |
| $Tp33$ (D,G)                           | -0.00471 | 0.00406 | 456.56 | -0.00226 | 0.00635 | 295.35 |
| $Tp34$ (D,S)                           | -0.00468 | 0.00411 | 450.95 | -0.00222 | 0.00635 | 295.36 |
| $Tp35$ (S,G)                           | -0.00479 | 0.00392 | 472.48 | -0.00235 | 0.0064  | 292.72 |
| $Tp36$ (S,D)                           | -0.00481 | 0.00388 | 477.45 | -0.00237 | 0.00647 | 289.82 |

#### 4. 2 Interpretation of the Results

The simulation results were interpreted in line with the primary objectives of the proposed modified regression-cum-dual mean imputation schemes: to reduce estimation bias, minimize Mean Squared Error (MSE), and improve the efficiency of population mean estimation under two-phase simple random sampling. To evaluate these objectives, extensive Monte Carlo simulation experiments were conducted under different sampling configurations and population characteristics. The performance of the proposed estimators was assessed using three standard measures—Bias, MSE, and Percentage Relative Efficiency (PRE)—which respectively measure estimation accuracy, precision, and relative efficiency.

The simulation results, presented in Tables 1 and 2 for Cases 1 and 2, compare the proposed estimators with existing estimators developed by Lee *et al.* (1994)  $T_1^*$ , Singh and Horn (2000)  $T_2^*$ , Kadilar and Cingi (2008)  $T_3^*$ , Singh (2009)  $T_4^*$ , Audu *et al.* (2021b)  $T_{5(j)}^*$ ,  $j = 1, 2, 3, 4$  and Musa *et al.* (2023)  $T_{6(j)}^*$ ,  $j = 1, 2, 3, 4$  ..

The comparative analysis shows that estimators with smaller absolute Bias values are more accurate, lower MSE values indicate greater precision, and higher PRE values reflect superior efficiency.

Accordingly, the interpretation focuses on these performance measures to determine the extent to which the proposed modifications outperform the existing estimators and achieve their intended objective of improving population mean estimation under two-phase simple random sampling.

#### V. CONCLUSION

This study developed a class of modified regression-cum-dual mean imputation estimators for estimating population means under two-phase simple random sampling by effectively incorporating auxiliary information into the imputation process. The primary objective was to improve the accuracy and efficiency of population mean estimation in the presence of missing observations. The statistical properties of the proposed estimators, particularly their Biases and Mean Squared Errors (MSEs), were derived up to the third-order approximation using Taylor series expansion, providing a rigorous theoretical framework for evaluating their performance and establishing efficiency conditions relative to existing estimators.

The theoretical findings were validated through extensive Monte Carlo simulation studies conducted under different population structures and sampling configurations. The results consistently showed that the proposed estimators produced lower Biases, smaller MSEs, and higher Percentage Relative Efficiencies (PREs) than the competing estimators across all simulation scenarios. These findings confirm the robustness, stability, and superior performance of the proposed estimators under varying survey conditions.

Overall, the study demonstrates that the modified regression-cum-dual mean imputation schemes provide more accurate, precise, and efficient estimates of the population mean than existing methods. The proposed estimators represent a significant methodological contribution to survey sampling and offer a practical approach for handling missing data in socio-economic, agricultural, health, and official statistical surveys where auxiliary information is available.

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